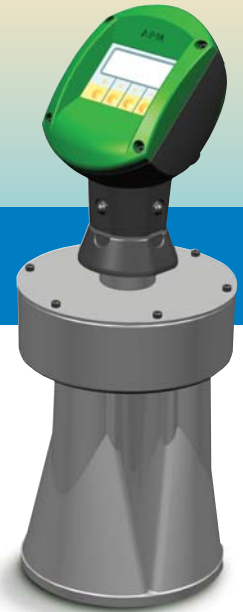


# 3D LevelScanner

# M

## OPERATING INSTRUCTIONS

Level measurement in  
solid applications with  
mapping capabilities



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# 1 About this document

This operation manual provides complete instructions for quick setup and safe operation of the 3DLevelScanner M. This manual is designed for trained personnel. Please read it carefully before you proceed.

## 1.1 Symbolism used

Information, tip, note



### **Additional information**

Indication of helpful Additional information



### **Caution, warning, danger**

Indication of a potentially dangerous situation, which could result in injury or damage.



### **Ex applications**

Indication of special instructions for Ex applications.

## 1.2 For your safety

### 1.2.1 Authorized personnel

All operations described in this manual must be carried out by authorized trained personnel only. For safety and warranty reasons, any internal work on the devices must be carried out by manufacturer-authorized personnel only.

### 1.2.2 Appropriate use

The 3DLevelScanner M is a sensor designed for continuous level measurement.

### 1.2.3 Warning about misuse

Inappropriate or incorrect use of the device can give rise to application-specific hazards, e.g., vessel overfill or damage to system components through incorrect mounting or adjustment.

### 1.2.4 General safety instructions

The 3DLevelScanner is a high-tech device requiring strict observance of standard regulations and guidelines. The user must take note of the safety instructions in this operating manual, as well as country-specific installation standards (e.g., the VDE regulations in Germany) and all common safety regulations and accident prevention rules.

### 1.2.5 CE conformity

The 3DLevelScanner conforms to CE's EMC and NSR standards; and. CE conformity is as follows:

**EMC:**

- Emission EN 61326: 1997 (class B)
- Susceptibility EN 61326: 1997/A1: 1998

**NSR:** EN 61010-1: 2001

### 1.2.6 Safety information for Ex areas



Please note the Ex-specific safety information for installation and operation in Ex areas. These safety instructions are part of the operating instructions manual that comes with Ex-approved devices.

### 1.2.7 Environmental instructions

Protection of the environment is one of our most important duties. Please help us fulfill this obligation by observing the environmental instructions in the following chapters of this manual:

- Storage and transport, page 7.
- Dismounting, page 34.

## 2 Product description

### 2.1 Delivery contents

- 3DLevelScanner M sensor
- Documentation
- Ex-specific safety instructions (with Ex versions)
- Certificates if applicable
- 3DLink Pro (Optional)
- HART Modem (optional)

### 2.2 Components

- Special horn antenna
- Process fitting (depending on the flange or thread version)
- Housing with electronics, optionally available with a plug connector and connection cable

The components are available in different configurations.

### 2.3 Theory of Operation

The APM 3DLevelScanner™ is an innovative new family of devices that continuously measure level, volume and mass of materials inside a silo or an open bin.

The 3DLevelScanner employs a 2-dimensional array-beam former to transmit low frequency pulses and receive echoes of the pulses from the contents of the silo, bin or any other container. The device's digital signal processor samples and analyzes the received signals. The processor uses the time and direction parameters of the received echoes to generate a 3-dimensional image of the surface, which can be displayed on a remote monitor. The system can accurately determine the volume and mass of material, enabling an unrivaled degree of process measurement and inventory control.

### 2.4 Wide Application Range

The 3DLevelScanner M measures practically any kind of solid material, stored in practically unlimited variety of containers, including large open bins, bulk solid storage rooms and warehouses, mapping loads that randomly form over time inside silos, and many other challenging applications that were not possible until now. The sensor can measure ranges of up to 70 m (230 ft) and generate 3D maps of the surface.

### 2.5 Advantages

- **Practice-oriented device versions** - The 3DLevelScanner M is available with both thread and flange fittings.
- **Unaffected by content properties** - Fluctuations in content composition or even complete content changes do not influence the measuring result. No special adjustment or calibration is necessary.
- **Service and maintenance-friendly** - Thanks to the non-contact measuring principles, the 3DLevelScanner M is particularly easy to service and maintain.

## 2.6 Storage and transport

The device is protected by special packaging during transport, and is guaranteed to handle normal loads during transport.

### 2.6.1 Storage and transport temperature

- For storage and transport temperature please see *Technical data, Ambient conditions, page 39*.
- Relative humidity: 20 - 85 %

## 3 Mounting

### 3.1 Installation position

Install the 3DLevelScanner M where you can easily reach it for mounting and connecting. You can install the housing in four different positions. In each position, the housing can be rotated 90°.

### 3.2 Moisture

Use the recommended cable (see *Connecting the power supply, page 13.*) and tighten the cable connection.

For additional protection against moisture, lead the connection cable downward in front of the cable entry. Rain and condensation water can thus drain off. This applies mainly to mounting outdoors, in areas where moisture is expected (e.g., by cleaning processes), or on cooled or heated vessels.

### 3.3 Measuring Range

The reference plane of the sensor measuring range is the seal surface of the thread or the lower side of the flange. All information regarding the measuring range as well as the internal signal processing relates to the reference plane.

#### NOTE:

If the container content reaches the antenna, buildup could form on it over time and cause measurement errors.

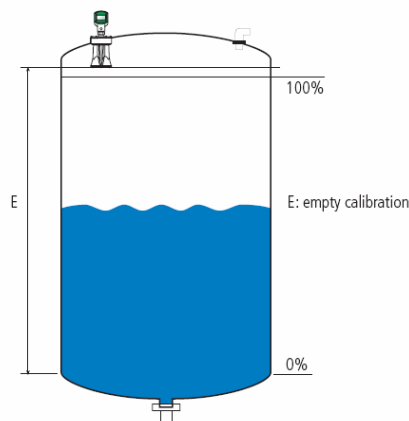


Figure 1: Measuring range

### 3.4 Pressure

The process fitting must be sealed if there is low pressure in the vessel. Before use, verify that the seal material is resistant to the medium. The maximum permissible pressure is stated in *Technical data, page 38*, and on the type label of the sensor.

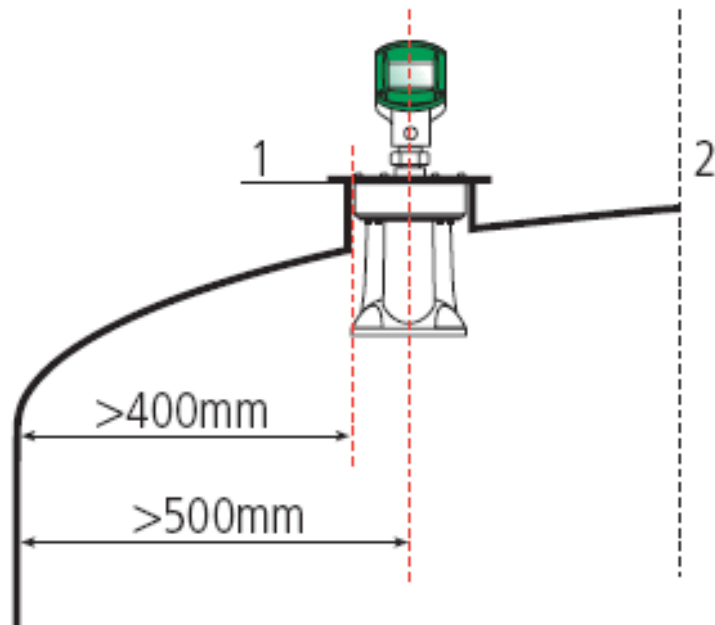
### 3.5 Installation Location

When mounting the 3DLevelScanner M, a distance of at least 400 mm from the vessel wall (500mm from the center of the scanner to the vessel wall) should be maintained. If the 3DLevelScanner M is installed in the center of the vessel, multiple echoes can occur.

---

**Note:** It's recommended **not** to install the 3DLevelScanner M in the center of the silo.

---



**Figure 2: Mounting on arched vessel tops**

1. Reference plane
2. Vessel center or symmetry axis

If this distance cannot be maintained, a false echo storage should be carried out. For more information see *False echo storage*, page 24. This applies particularly if buildup of residue on the vessel wall is expected.

---

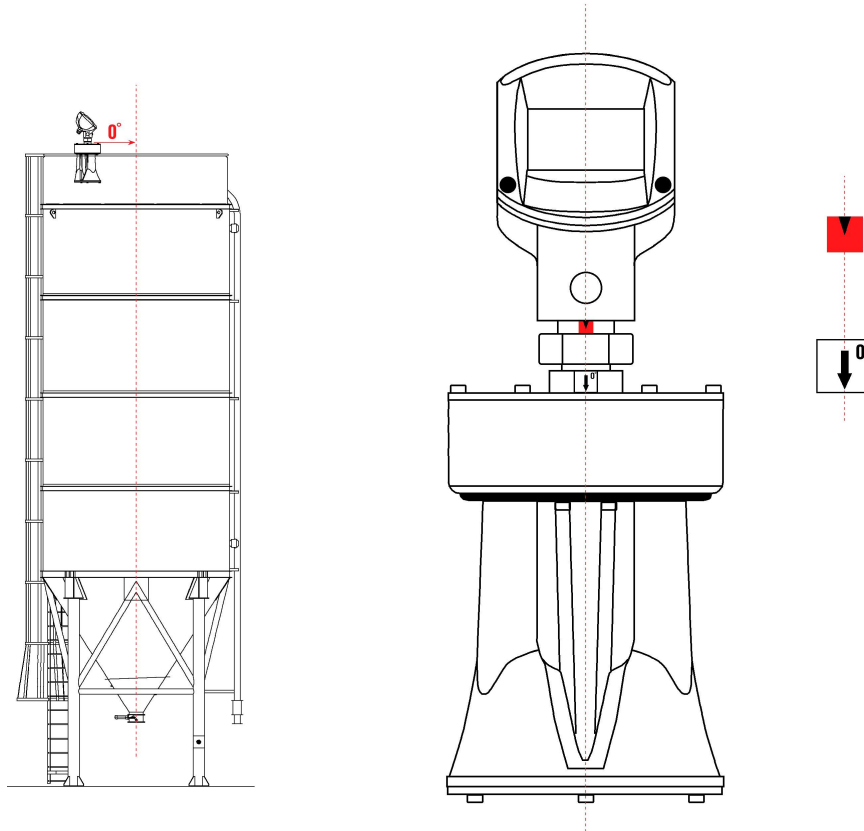
**Note:** It is very important to use "range of mapping" right after installation, in order to map all false echoes. The results are better when the silo is empty.

---

### 3.6 Mounting Direction

The 3DLevelScanner must be mounted in the right direction in order to scale and adjust the position of the unit.

The mounting direction is indicated by a sticker labeled  $0^0$  on the instrument (see image below). The  $0^0$  must point to the center of the vessel (including square vessels and open bins).



**Figure 3:  $0^0$  Sticker location**

---

**Note:** The direction of the mounting has no influence on 3DLevelScanner S (it only matters in M/MV versions). However, it is recommended to mount it correctly in any case for future upgrade to M or MV versions.

---

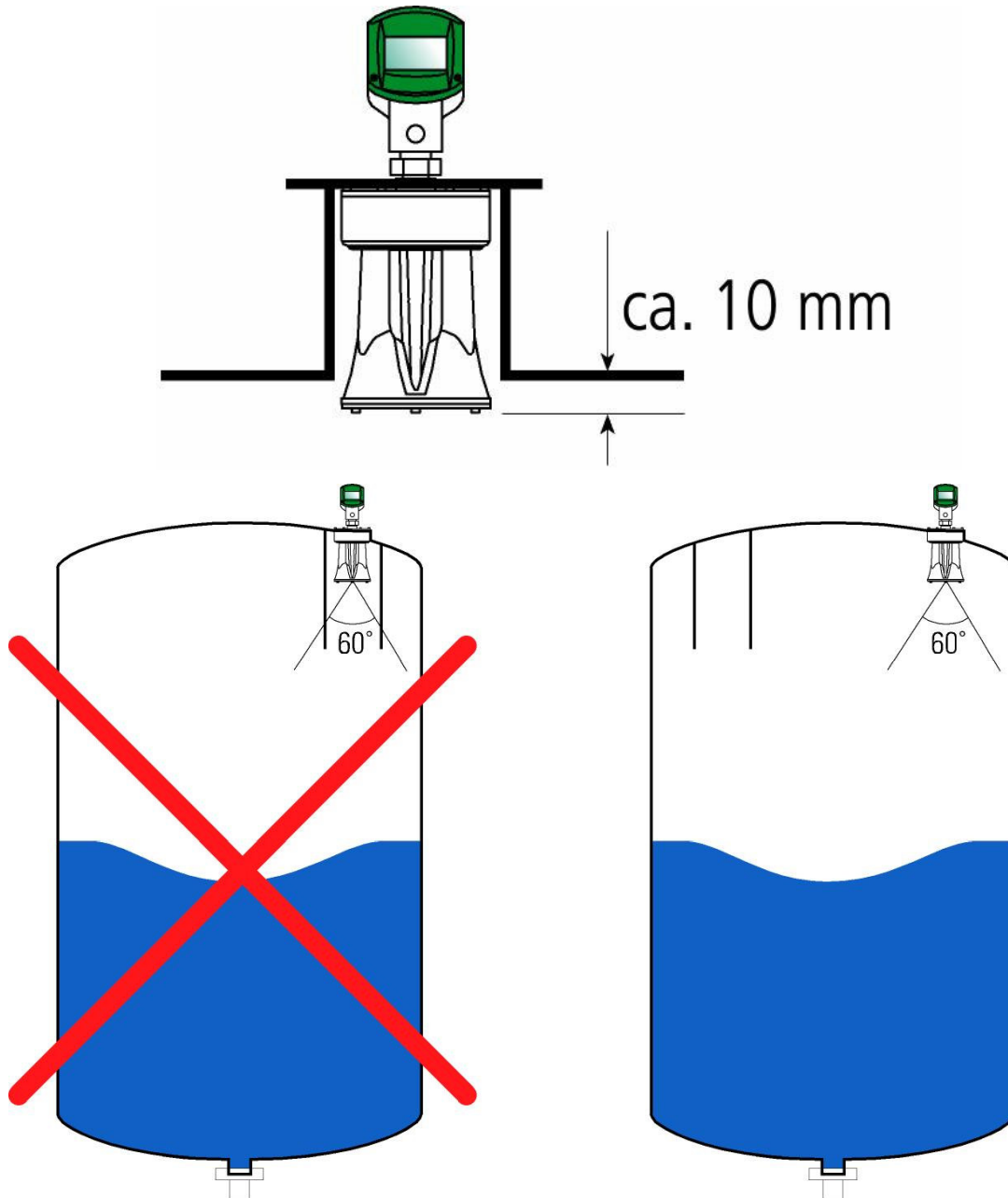
**3.7****Socket**

Socket pieces should be positioned so that the antenna end protrudes at least 10 mm (0.4 inch) out of the socket.

---

**Important Note:** Rails/frames should never interfere with the 60° beam angle transmitted and received (see figures below).

---



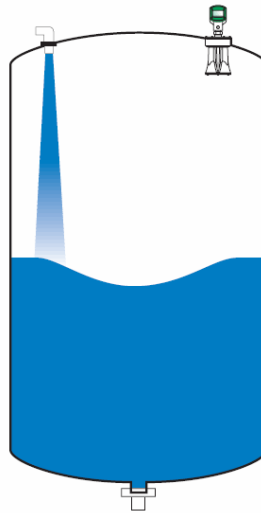
**Figure 4: Recommended socket mounting**

### 3.8 Sensor Orientation

The sensor will generate optimal performance if it is located halfway between the wall and the center of the silo.

### 3.9 Inflowing Material

Do not mount the devices in or above the filling stream. The optimal position is as far away from the inflowing material.



**Figure 5: Inflowing material**

## 4 Connecting the power supply

### Note on safety

Always observe the following safety instructions:

- Connect only in the complete absence of line voltage
- If overvoltages are expected, overvoltage arresters should be installed.



In hazardous areas you should take note of the appropriate regulations, conformity and type of approval certificates of the sensors and power supply units.

### 4.1 General Requirements

The power supply range can differ depending on the device version. See the *Technical data, page 38*, for full details.

### 4.2 Power Supply

- **4...20 mA/HART 4-wire**  
Power supply and signal current are carried on two separate connection cables.

#### 4.2.1 Connection Cable

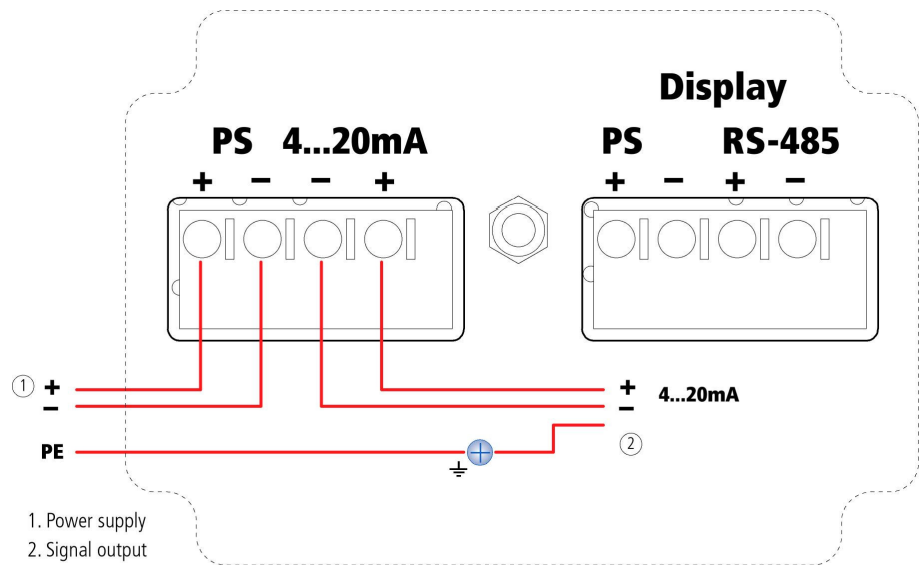
An outer cable diameter of 5...9 mm ensures the seal effect of the cable entry. If electromagnetic interference is expected, we recommend the use of screened cable for the signal lines.

### 4.3 Connection procedure

1. Unscrew the back cover
2. Loosen the compression nut of the cable entry.
3. Remove approx. 10 cm (4 in) of the cable mantle, strip approx. 1 cm (0.4 in) insulation from the ends of the individual wires.
4. Insert the cable into the sensor through the cable entry.
5. Push the terminals top with a screwdriver (see following illustration).
6. Insert the wire ends into the open terminals according to the wiring plan.
7. Let go of the terminal top.
8. Check the hold of the wires in the terminals by lightly pulling on them.
9. Connect the screen to the internal ground terminal and the external ground terminal to potential equalization.
10. Tighten the compression nut of the cable entry. The seal ring must completely encircle the cable.
11. Screw the back cover back on.

## 4.4 Wiring Plans

**4...20mA/  
HART 4-wire**



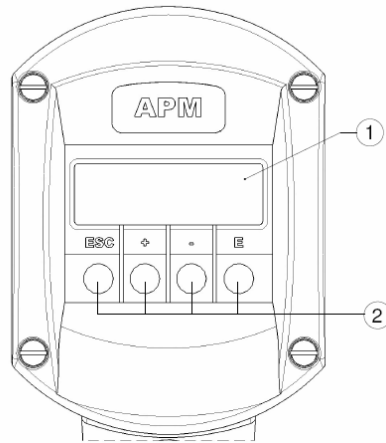
**Figure 6: Connection HART 4-wire**

## 5 Adjustment

The 3DlevelScanner M can be set up and operated using one of the following:

- The LCD panel
- A HART handheld device
- GSM communication using 3DLink Pro
- An adjustment software tool

### 5.1 Adjusting the 3DlevelScanner M Using the LCD Panel



**Figure 7: 3DlevelScanner M front panel LCD**

1. LCD
2. Adjustment Keys

**Adjustment keys:**



- Navigates downwards in the selection list
- Shifts to the right within a function



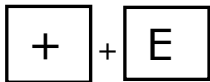
- Navigates upwards in the selection list
- Edit numeric values within a function



Navigates to the Left within a function group; Press **Esc** for 3 sec to go back to the default screen

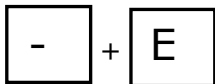


- Navigates to the right within a function group;
- Confirmation



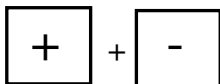
Increases the contrast of the LCD

Simultaneously



Decreases the contrast of the LCD

Simultaneously



**Hardware lock/unlock**

After a hardware lock, operation of the device via display or remote communication is not possible.

The hardware can only be unlocked via the display, and an unlock parameter must be entered to do so.

The display continues – uninterrupted.

When all three buttons are pressed the message “Hardware locked” is displayed.

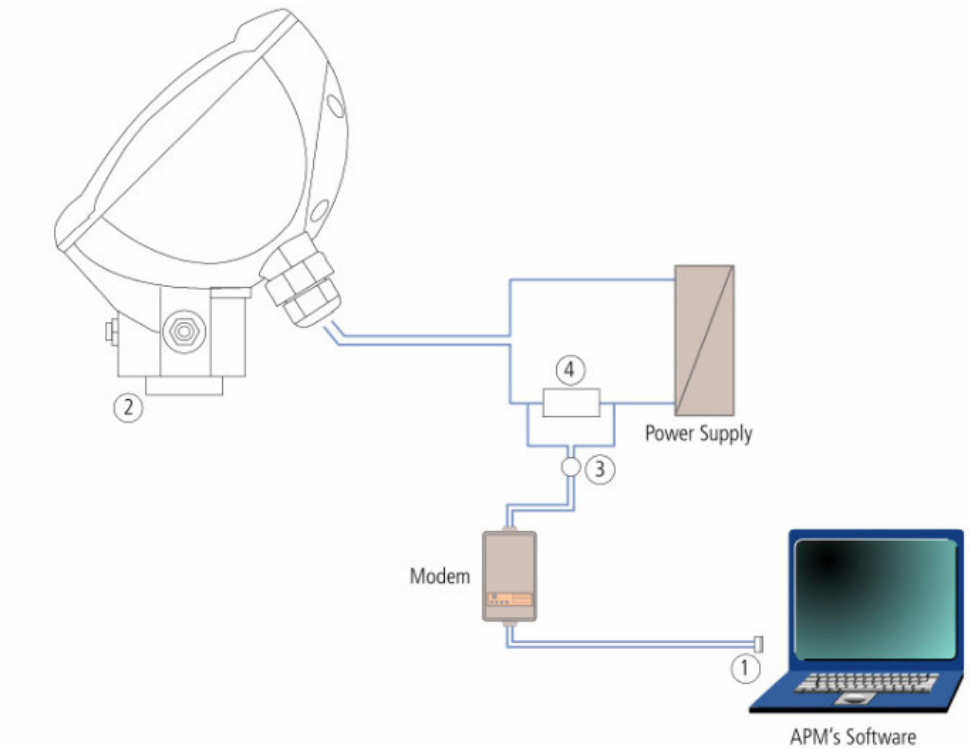
When all three buttons are pressed again, the message “unlock parameter.” Appears. Enter the unlock parameter (100) and confirm by pressing E.



Simultaneously

## 5.2 Adjusting the Scanner Using the Software Tool

The 3DLevelScanner M can be configured and operated via APM's Software Tool. Connect the 3DLevelScanner M according to the following diagram:



**Figure 8: Software Tool connection**

1. RS-232/USB connection
2. 3DLevelScanner M
3. HART Adapter cable
4. HART Resistance—250 ohm

---

For specific instructions on adjusting parameters with APM's software tool, please see the "APM 3DLevel Manager Software Operating Instructions" manual.

---

## 6 Operation

### 6.1 Operating Menu

The operating menu consists of two levels:

1. **Function groups** (00, 01, 03, ..., 0C, 0D)

The device's functions are organized in function groups. The available function groups are: *basic setup*, *safety settings*, *output*, *display*, *system parameters*, *diagnostics*, *extended calibration*, *linearization*, *temperature*.

2. **Functions** (001, 002, 003, ..., 0D8, 0D9)

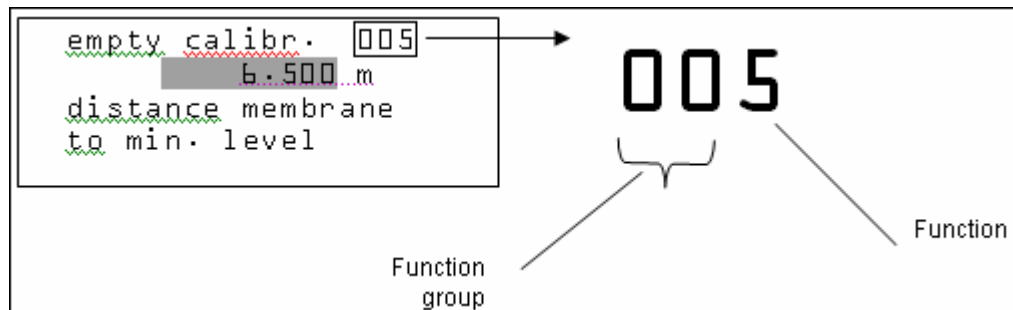
Each function group consists of one or more functions. The functions perform actions or set up the device's parameters. Numerical values can be entered and parameters can be selected and saved. The available functions of the *basic setup* function group (00) include: *media type* (002), *process cond.* (004), *empty calibr.* (005), etc.

For example, if you wish to change the media type, do the following:

- Select the *basic setup* (00) function group.
- Select the media type (002) function (where the existing media type is selected).

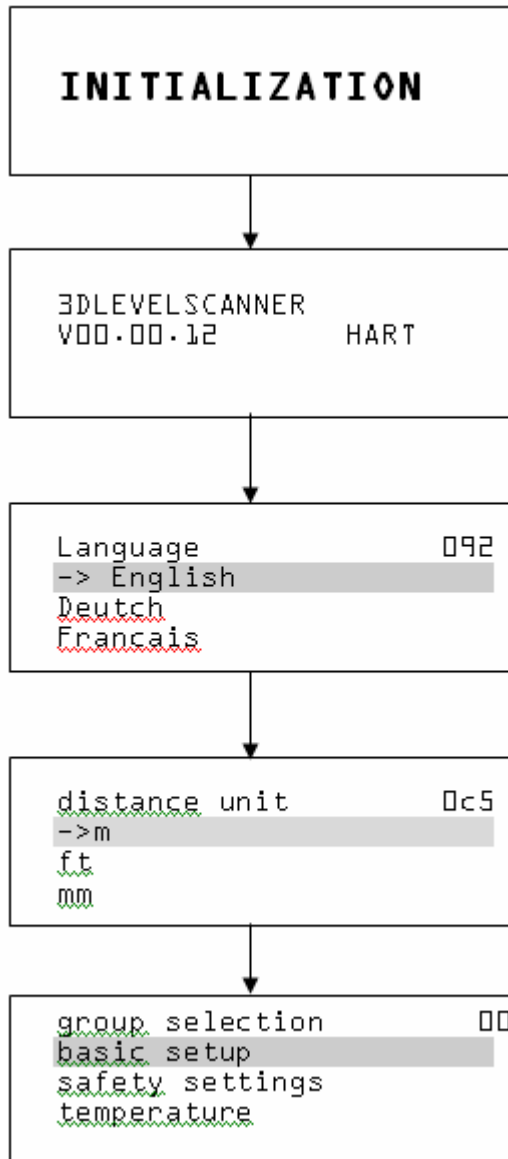
### 6.2 Function indication

A three digit identifier is displayed on the right-hand side of the function on the display. The first two digits identify the function group. The third digit indicates the individual function within the function group.



### 6.3 Switching on

After 3DLevelScanner M is connected to the power supply, it carries out a self-test for approx. 30 seconds. After the initialization is complete, the following is displayed, allowing you to select a language and distance units.



After 30 seconds, the following message appears:

Vxx.yy.zz Prot.

xx – hw version

yy – sw version

zz – sw version

prot – HART (Protocol name)

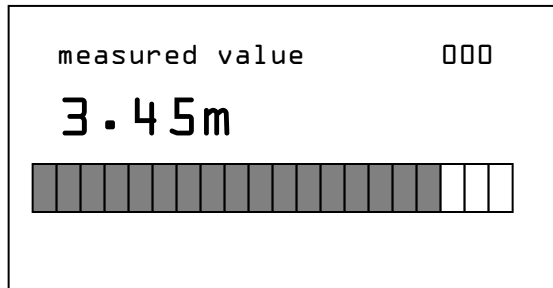
After five seconds or after pressing , you will be presented with language selection: (appears on the first time the device is switched on): Use the +/- to select the desired language and press .

Select the distance units (this selection appears on the first time the device is switched on)


Press  to reach the group selection. This selection enables you to perform the basic setup.

## 6.4 Basic/Default Screen

After startup the following screen is displayed:



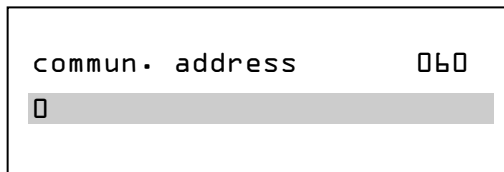
Press  to reach the group selection menu.

Press  for 3 seconds to return to the measured value basic screen

## 6.5 Setup procedure

### 6.5.1 Address setting for several sensors on one input - HART-Multidrop

If several sensors are connected on one input, the address must be set before continuing with parameter adjustment. This is done in HART-Multidrop mode. For detailed description please see the "Description of Instrument Functions" manual.



Enter the communication address for the device with this function.

- Standard: 0 (if using 4-20mA)
- Multidrop: 1-15 (fixed current only)

### 6.5.2 Parameter adjustment

Because the 3DLevelScanner M is primarily a distance measuring device, the distance from the sensor to the product surface is measured. In order to have the actual product level displayed, an allocation of the measured distance to the height percentage must be carried out. To make this adjustment, the full and empty distances in the vessel are entered. The seal surface of the thread or flange is always the reference point for these distance values. The actual level is then calculated on the basis of the entered values. At the same time, the operating range of the sensor is limited from maximum range to the required range.

The actual product level during this adjustment is not important, because the min./max. adjustment are always performed without changing the product level. These settings can be made in advance without having to install the device first.

The individual submenu items in the main menu item "*Basic adjustment*" should be selected one by one and updated with the correct parameter values.

Start your parameter adjustment with the following menu items of the basic adjustment.

### 6.5.3 Medium selection

Each product has different reflective properties. In solids, they are determined by dust generation, material cones and additional echoes caused by the vessel wall. Selecting the correct medium will ensure optimal adaptation of the sensor to the product and significant increase in accuracy, particularly for products with bad reflective properties.

```
media type      001
->HF
Solid
Solid SA
```

This function is used to select the media type:

- HF (High Frequency)
- Solid

Enter the requested parameter via the appropriate keys, save your settings and move on to the next menu item with the **[E]** key.

### 6.5.4 Process Conditions

The process conditions are another factor that influences the measurement. To adapt the sensor to the process conditions, this menu offers several options.

```
Process cond.  000
->standard
Fast change
Slow change
```

Enter the requested parameter via the appropriate keys, save your settings and move on to the next menu item with the **[E]** key.

### 6.5.5 Performing empty calibration adjustment

1. Move from the measured value display to the main menu by pressing **[E]**.

```
group selection 00
->basic setup
safety settings
linearization
```

2. Select the *Basic setup* menu with **[→]** and confirm with **[E]**. Now select the Empty Calibr. with **[→]** and confirm with **[E]**. The "Empty calibr." menu is displayed.

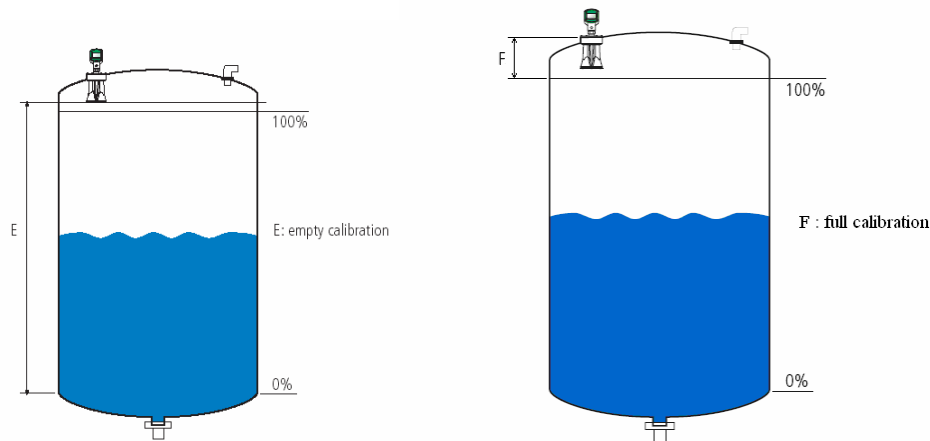
```

empty calibr.      005
┌──────────────────┴──────────────────┐
6.500 m
distance flange
to min. level

```

This function is used to enter the distance from the **flange** (reference point of the measurement) to the minimum level (=zero).

Enter the requested parameter via the appropriate keys, save your settings and move on to the next menu item with the **[E]** key.



**Figure 9: Empty Calibration**

3. Enter the appropriate distance value in **DU** (corresponding to the percentage value) for the empty vessel (e.g., distance from the sensor to the vessel bottom).
4. Save the settings by pressing **[E]** and move on to "Full Calibr".

### 6.5.6 Performing Full Calibration adjustment

Proceed as follows:

```

full calibr.      006
┌──────────────────┴──────────────────┐
┆.75m
distance flange
to max. level

```

This function is used to enter the distance from the **bottom of flange (measurement reference point)** to the maximum level (**100%**).

**CAUTION!**

The maximum level may not project into the blocking distance (BD). If the BD is compromised, it may cause device malfunction. After basic calibration, enter a safety distance (SD) in the safety distance (015) function. If the level is within this SD, the 3DLevelScanner M signals a warning or an alarm, depending on your selection in the 'in safety distance' (016) function.

1. Enter the appropriate distance value in m and save with **[E]**.
2. Save the settings with **[E]**

**At this point, the basic adjustment is complete.**

## 7 False echo storage

High sockets or vessel installations, such as struts or agitators as well as buildup and weld joints on the vessel walls, cause interfering reflections which can impair the measurement. False echo storage detects and marks these false echoes, so that they are no longer taken into account in level measurement. A false echo memory should be created with an empty vessel so that all potential interfering reflections will be detected.

### 7.1 Range of mapping function (052)

range of mapping	052
0.000 m	
Input of	
Mapping range	

This function displays the suggested range of mapping. The reference point is always the reference point of the measurement (see Function 005). This value can be edited by the operator for manual mapping. The default value is 0 m.

#### **CAUTION!**

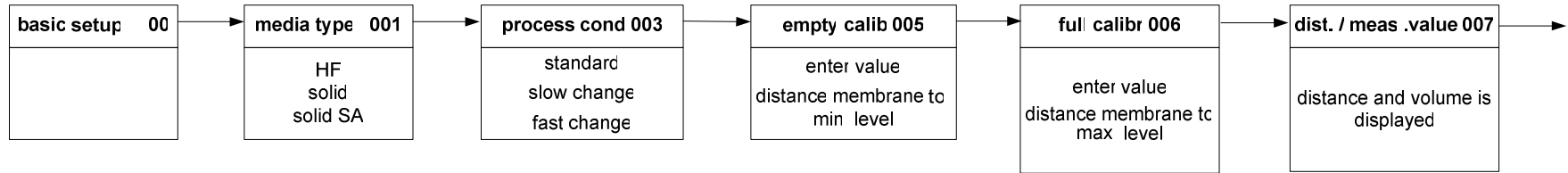
The range of mapping must end 0.5 m before the echo of the actual level. For an empty vessel, do not enter E, but E - 0.5 m. If a mapping already exists, it is overwritten up to the distance specified in the range of mapping (052). Beyond this value the existing mapping remains unchanged.

## 8 Optional settings

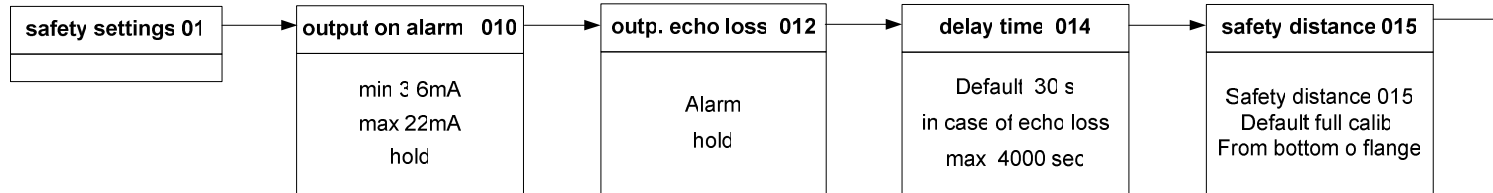
Additional adjustment and diagnosis options such as scaling and simulation are shown in the following menu diagrams. You will find a detailed description of these menu items in the "3DLevel Manager Software Operating Instructions" manual.

All the menus and submenus in the LCD exactly match the menus in the 3DLevel Manager software. It is preferable and more comfortable to make all the configurations in the 3DLevel Manager after mounting and connecting the unit.

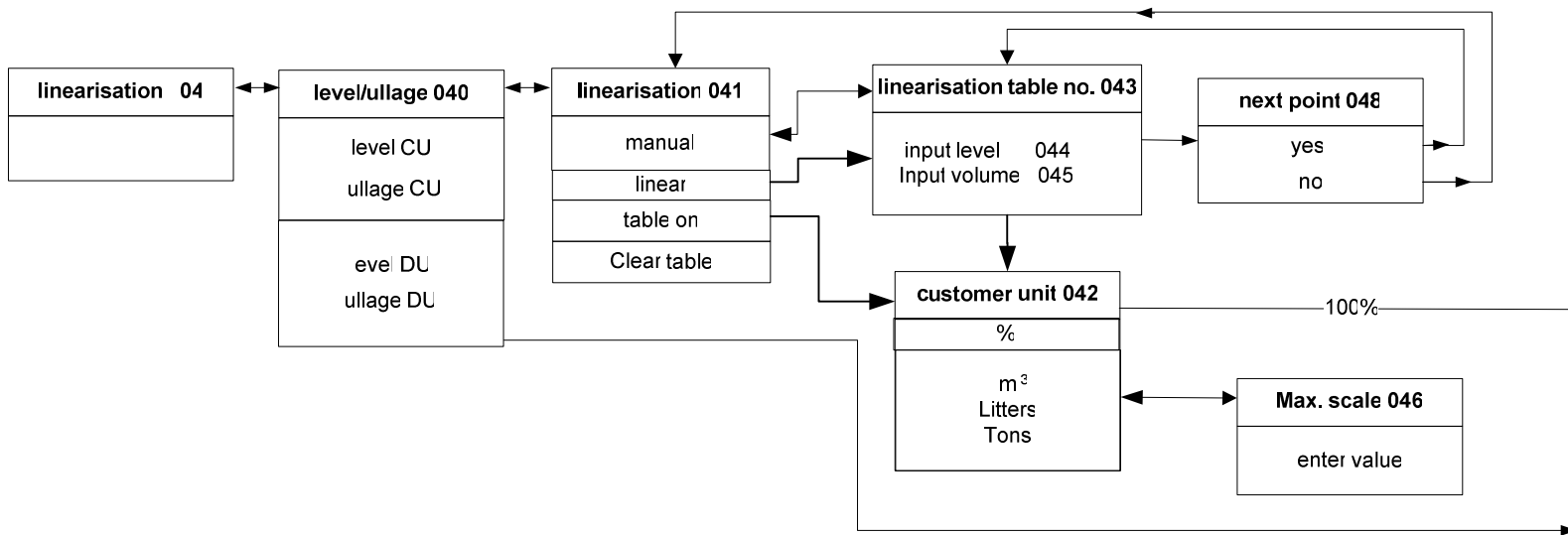
### 8.1 Basic/default displayed screen



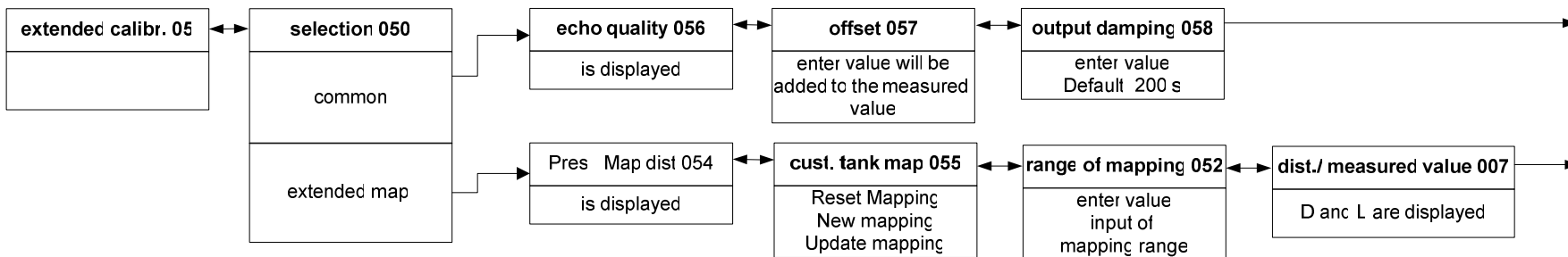
### 8.2 Safety settings screen



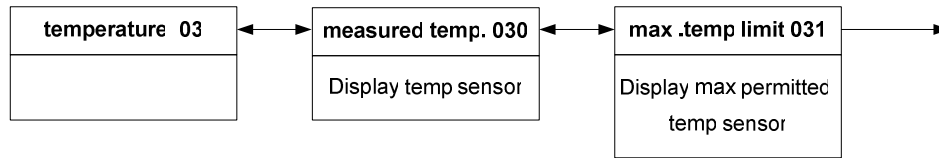
### 8.3 Linearization screen



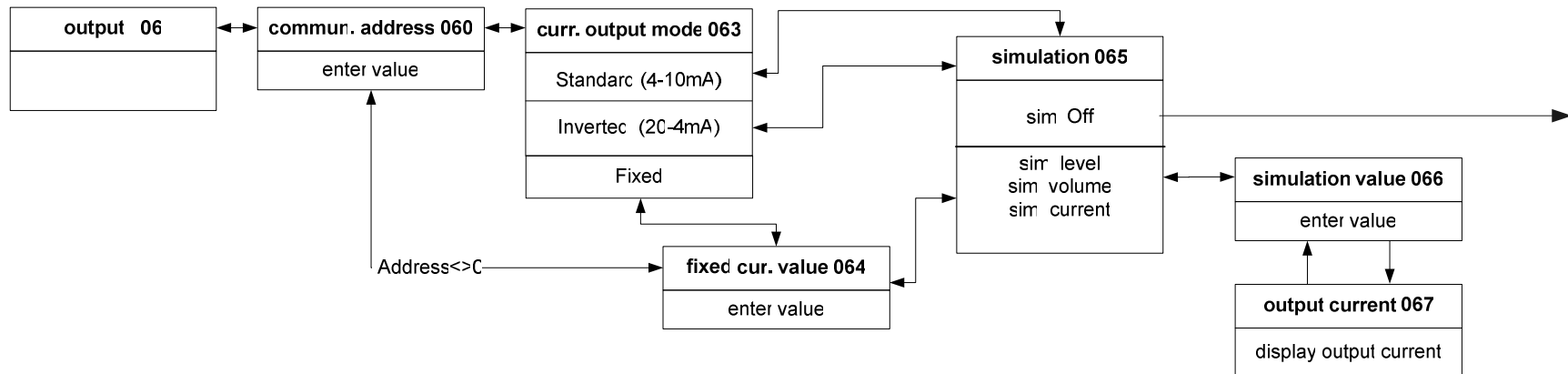
### 8.4 Extended calibration screen



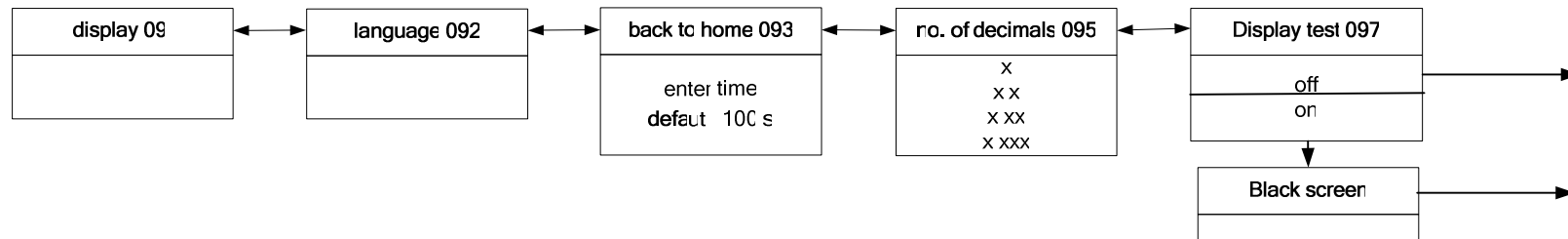
### 8.5 Temperature screen



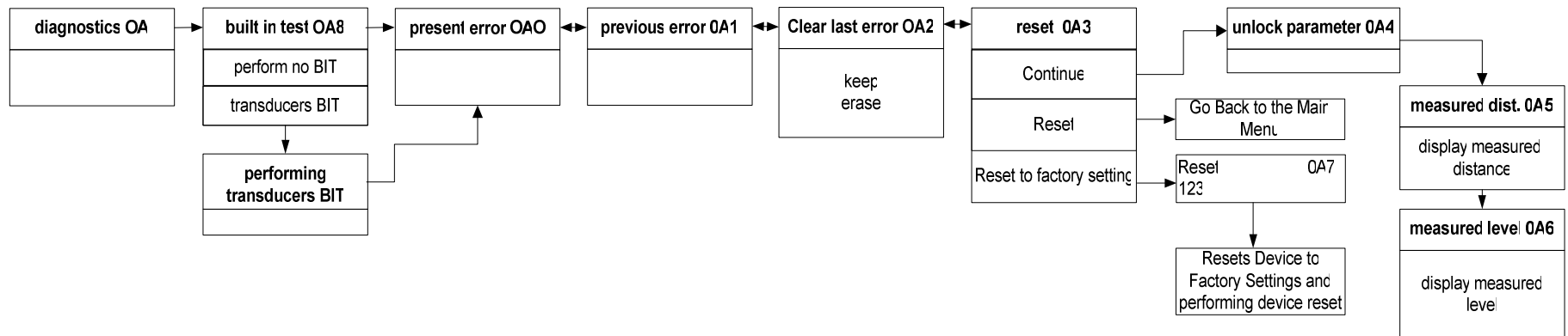
### 8.6 Output screen



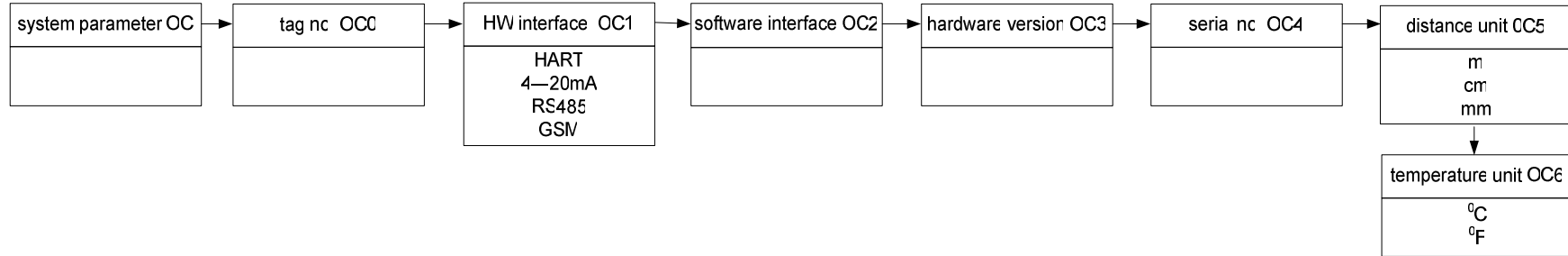
### 8.7 Display screen



### 8.8 Diagnostics screen

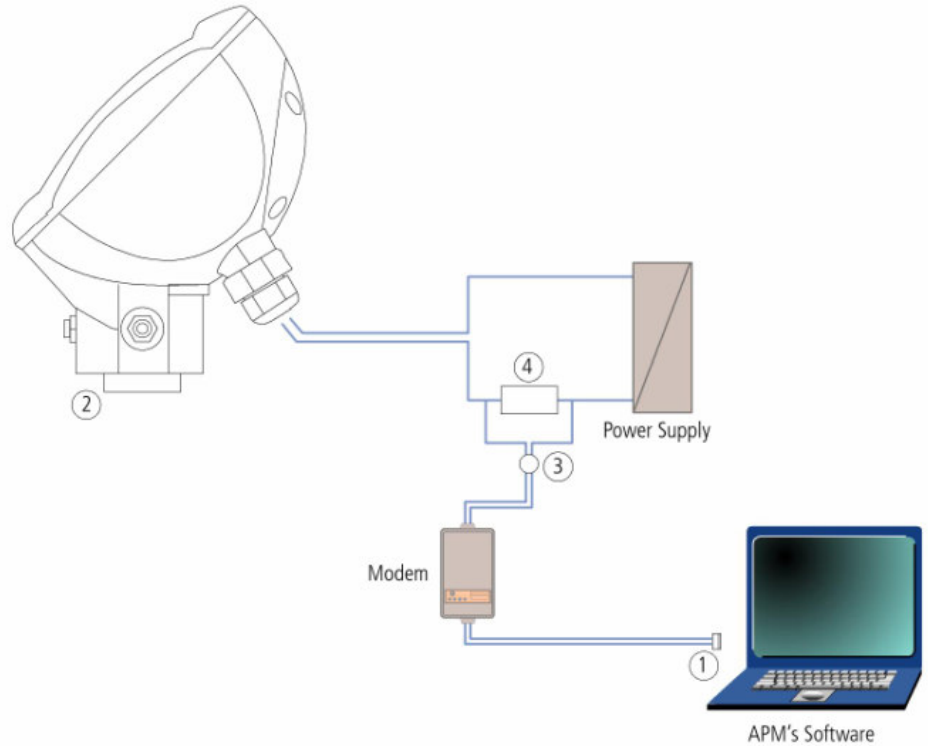


### 8.9 System parameter screen



## 8.10 Adjusting Using the Software Tool

The 3DLevelScanner M can be configured and operated via APM's Software Tool. Connect the 3DLevelScanner M according to the following diagram:



**Figure 10: Connecting the Software Tool**

1. RS-232/USB connection
2. 3DLevelScanner M
3. HART Adapter cable
4. HART Resistance—250 ohm

### 8.10.1 Parameter adjustment with APM's Software Tool

Further setup steps are described in the operating manual *APM 3DLevel Manager software operating instructions* included with each CD, which can also be downloaded from our Web site.

## 9 Maintenance and fault rectification

### 9.1 Maintenance

When used as directed in normal operation, the 3DLevelScanner M is completely maintenance-free.

### 9.2 Fault rectification

Causes of malfunction

The 3DLevelScanner M is highly reliable. Nevertheless, faults can occur during operation. Faults may be caused by the following:

- Sensor
- Process
- Power supply
- Signal processing.

The first measures to be taken are to check the output signal and evaluate the failure messages via the LCD. The procedure is described below. More comprehensive diagnostics can be performed by connecting the scanner to the 3DLevel Manager and using the BIT's in the diagnostic group (in the *APM 3DLevel Manager software operating instructions*). In many cases the fault reasons can be determined and rectified using this method.

#### 9.2.1 24 hour service hotline

If you fail to solve the problem with the methods suggested here, please call in urgent cases the APM service hotline at **+972 3 6488891**

The hotline is available 7 days a week around the clock. Since we offer this service world-wide, the support is only available in the English language. The service is free of charge, except for standard (international) telephone costs.

#### 9.2.2 Checking the 4 ... 20 mA signal

Connect a hand-held multimeter with a suitable measuring range according to the wiring plan.

? 4 ... 20 mA signal not stable

Possible Problem: level fluctuation

Solution: set integration time via LCD or APM's Software.

? 4 ... 20 mA signal missing.

Possible Problem: incorrect connections

Solution:

Check connection according to *Connection procedure, page 13*, and correct, if necessary, according to the wiring plan, see *Wiring Plans, page 14*.

Possible Problem: No power supply

Solution: Check cables for line break, repair if necessary.

Possible Problem: Supply voltage too low or load resistance too high

Solution: Check and adapt, if necessary.

? Current signal greater than 22 mA or less than 3.6 mA

Possible Problem: Electronics module defective

Solution: Exchange device or return it for repair.

### 9.2.3 Fault messages via the LCD

? E1

Definition: No measured value available.

Possible Problem: Sensor in boot phase

Possible Problem: Sensor does not detect an echo, e.g., because of faulty installation or incorrect parameter adjustment.

? E2

Definition: Adjustment span too small

Solution:

Perform a new adjustment and increase the distance between the minimal and maximal adjustment.

? E3

Definition: No operable sensor software

Solution: Perform a software update or return the device for repair.

? E4

Definition: Hardware error, electronics is defective

Solution: Exchange device or return it for repair.

## 9.3 Replacing the electronics

If the electronics module is defective, it can be replaced by the user.

If there is no electronics module available on site, it can be ordered from your local APM agency.

## 9.4 Device repair

If it is necessary to repair the 3DLevelScanner please proceed as follows:

Download a return form from our Web site [www.apm-solutions.com](http://www.apm-solutions.com), under "*Services – Downloads – Repair form*".

By doing this you help us carry out the repair quickly and without having to call back for additional information.

- Print and fill out one form per device.
- Clean the device and pack it damage-proof.
- Attach the completed form and optionally a safety data sheet to the device.
- Send the device to the address of your local agency.

## 10 Dismounting

### 10.1 Dismounting procedure



#### **Warning!**

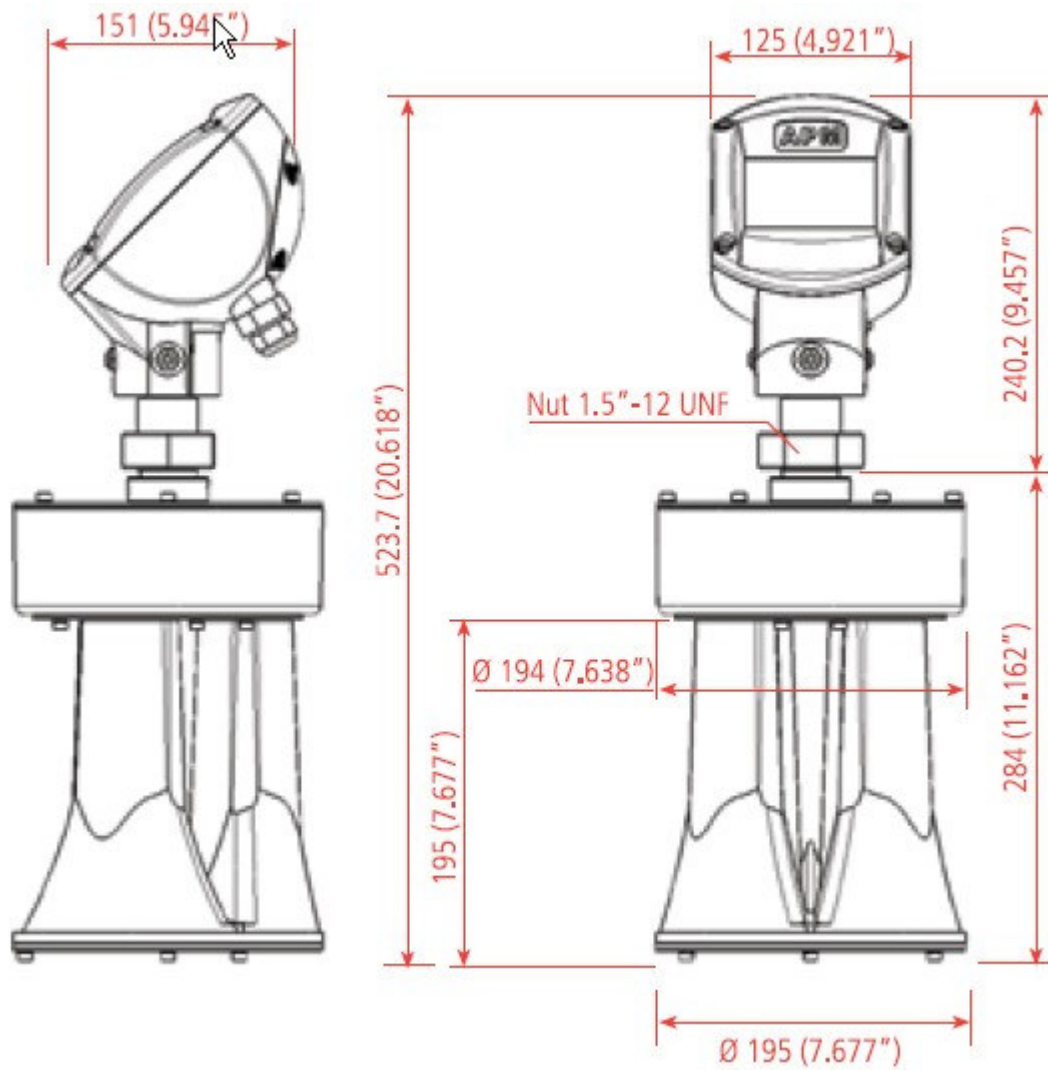
Before dismounting, be aware of dangerous process conditions such as pressure in the vessel, high temperature, corrosive or toxic products etc.

Take note of the chapters *Mounting, page 8*, and *Connecting the power supply, page 13*, and carry out the listed steps in reverse order.

We have specifically designed the electronic modules to be easily separable. Mark the device as scrap and dispose of it according to government regulations (electronic scrap ordinance).

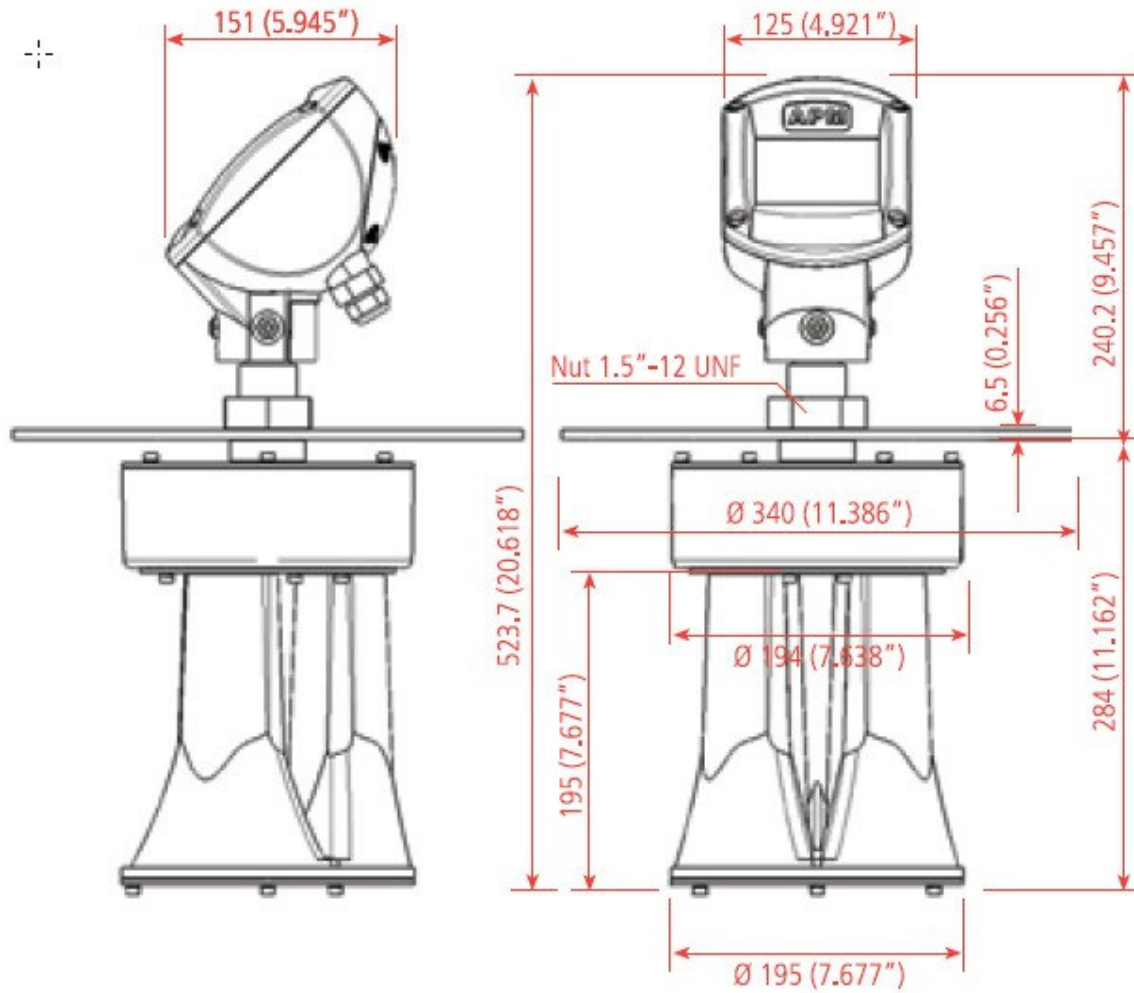
If you cannot dispose of the device properly, please contact us about disposal methods, or return.

# 11 Dimensions



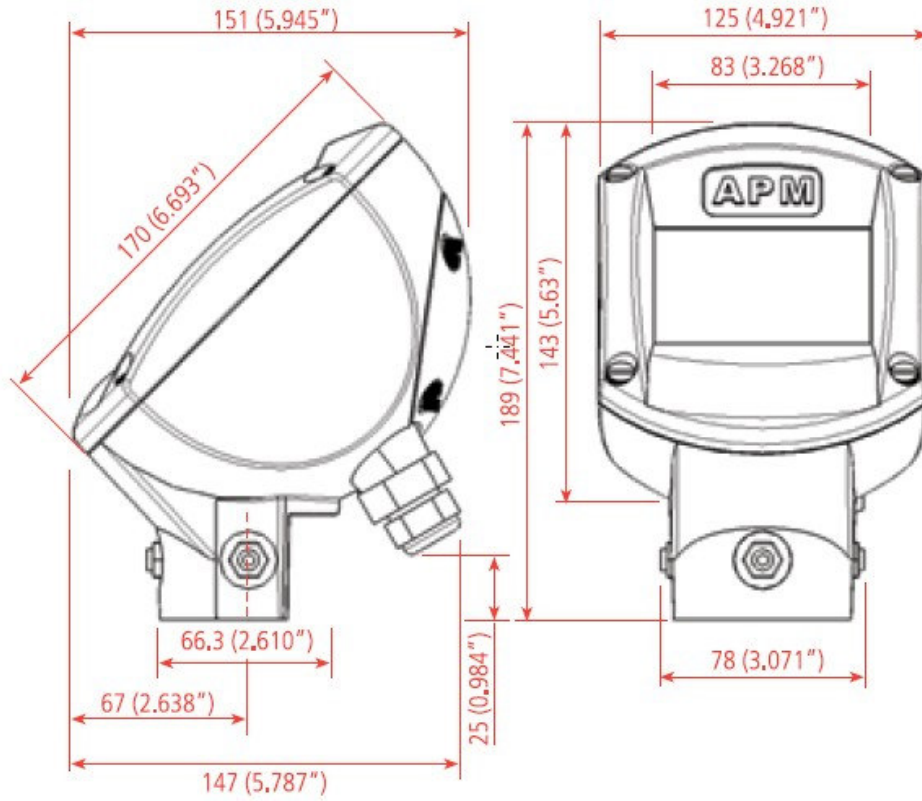
**Figure 11: 3DLevelScanner M with horn antenna in threaded version**

Dimensions are in mm (inch).



**Figure 12: 3DLevelScanner M with horn antenna in flange version**

Dimensions in are mm (inch).



**Figure 13: 3DLevelScanner M housing**

Dimensions are in mm (inch).

## 12 Appendix

### 12.1 Technical data

#### Materials, non-wetted parts

Housing	Alu-die casting powder coated.
Inspection window in housing cover	Polycarbonate
Antenna	Alu
Flange	Steel
Ground terminal	Stainless steel 1.4571/1.4435

#### Weight

9.9 kg ...11.4 kg	Depending on the flange size and housing (Alu, SS)
-------------------	--

#### Output variable

Output signal	4...20mA/HART/RS485/Modbus
Resolution	1.6 $\mu$ A
Fault signal	Current output unchanged, 22mA, >3.6 mA (adjustable)
Current limitation	22mA

#### Load

4-wire sensor	See load diagram
Integration time	0...9999 s, adjustable

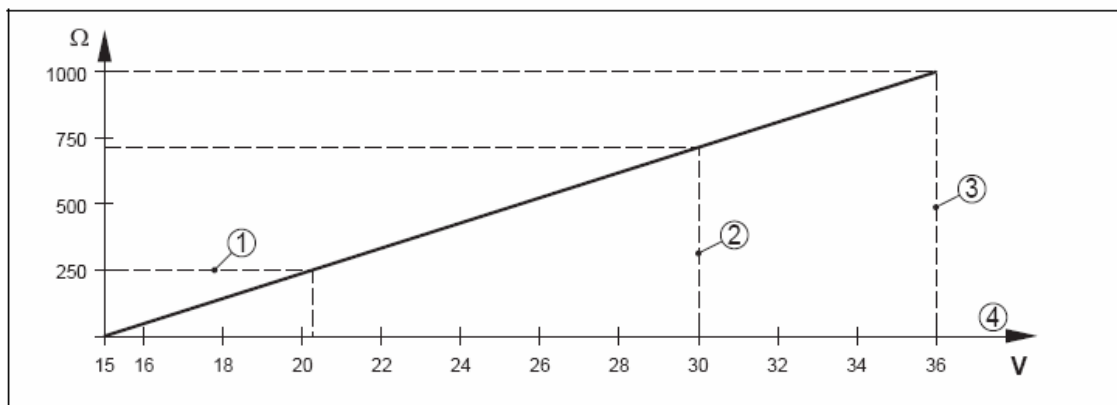


Figure 14: Voltage diagram

5. HART Load
6. Voltage Limit EEx ia device
7. Voltage limit non-Ex/Exd ia device
8. Supply Voltage

**12.2 Ambient conditions**

Ambient, storage and transport temperature: -40...85°C (-40...+176°F)

**12.3 Process conditions**

Vessel pressure: -0.2 ... 1 bar  
(-20...100 kPa or -2.9 ... 14.5 Psi)

**12.4 Process temperature**

Measured on the process fitting: -40...85°C (-40...203°F)

Vibration resistance: Mechanical vibrations with 4g and 5...100 Hz

**12.5 Electromechanical data**

Cable entry/plug: 1 x cable entry M20x1.5 (cable-Ø 5...9mm), 1 x blind stopper M20x1.5

or

1 x closing cap ½NPT, 1xblind stopper ½NPT

**Display panel**

LCD 4 lines x 20 characters

Adjustment elements 4 keys

Protection (inside sensor without cover) IP40

**Power supply – 4-wire device****4...20 mA/HART**

Supply voltage 20...32 VDC

Power consumption max 4VA; max 2.1 W

**Electrical protective measures**

Protection IP 66/67

**Approvals**

ATEX ATEX II ½D, 2D, Ex ibD/iaD 20/21 T110°C

FM FM Intrinsic safety (pending)

CSA CSA Intrinsic safety (pending)

IECM IEC EEx ia IIC T6 (pending)

**CE**

EMC

- Emission EN 61326: 1997 (class B)

- Susceptibility EN 61326:1997/A1: 1998

NSR (73/23/EWG) EN 61010-1: 2001

**FCC**

Conformity

to part 15 of the FCC regulations

FCC 47 CFR part 15:2007, subpart B, class A

**Measurement characteristics**

Temperature measurement accuracy

0.5° K

Frequency

3-10 kHz

Beam angle with horn antenna

60 degrees

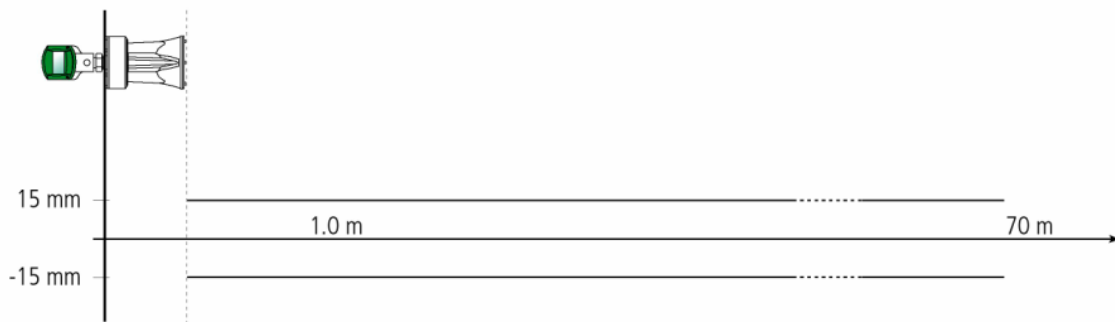
Interval

>2 s (dependent on the parameter adjustment)

Adjustment time

>3 s (dependent on the parameter adjustment)

**Accuracy (see diagram)**



**Figure 15: Accuracy**

# OPERATING INSTRUCTIONS

You can find at

**[www.apm-solutions.com](http://www.apm-solutions.com)**

downloads of the following:

- **Brochures**
- **Data Sheets**
- **Operating instructions manuals**
- **Software**
- **Certificates**
- **Product information**

and much, much more



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Represented by



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